GENERAL INFORMATION
This equipment is destined for use by professionals. The user should read this instruction manual and any other additional information supplied by Agilent before operating the equipment. Agilent will not be held responsible for any events occurring due to non-compliance, even partial, with these instructions, improper use by untrained persons, unauthorized interference with the equipment or any action contrary to that provided for by specific national standards. The SQ405 is a high voltage feeder used to feed the ionic pumps.

The following paragraphs contain all the information necessary to guarantee the safety of the operator when using the equipment. Detailed information is supplied in the section "Technical Information".

This manual uses the following standard protocol:

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**WARNING!**

The warning messages are for attracting the attention of the operator to a particular procedure or practice which, if not followed correctly, could lead to serious injury.

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**CAUTION**

The caution messages are displayed before procedures which, if not followed, could cause damage to the equipment.

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**NOTE**

The notes contain important information taken from the text.

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STORAGE
When transporting and storing the Controller, the following environmental requirements should be satisfied:

- temperature: from -20 °C to + 70 °C
- relative humidity: 0 - 95% (without condensation)

PREPARATION FOR INSTALLATION
The controller is supplied in a special protective packing. If this shows signs of damage which may have occurred during transport, contact your local sales office. When unpacking, ensure that the module is not dropped or subjected to any form of impact. Do not dispose of the packing materials in an unauthorised manner. The material is 100% recyclable and complies with EEC Directive 85/399.

INSTALLATION

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**WARNING!**

The controller is equipped with a 3-wire power cord. Use this power cord in conjunction with a properly grounded power socket to avoid electrical shock. High voltage developed in the controller can cause severe injury or death. Before servicing the unit, disconnect the input power cable.
NOTE

The controller must be installed inside a rack module, but it must be positioned so that free air can flow through the holes. Do not install or use the controller in an environment exposed to atmospheric agents (rain, snow, ice), dust, aggressive gases, or in explosive environments or those with a high fire risk.

During operation, the following environmental conditions must be respected:
- temperature: from 0 °C to +45 °C
- relative humidity: 0 - 95%
  (without condensation)

To connect the controller to the pump use the specific cable supplied with the controller.

The following paragraph describes the fundamental operating procedures.
Make all vacuum manifold and electrical connections and refer to the pump instruction manual prior to operating the controller.

**Power Failure**
In the event of a power failure (momentary or long period) the controller is switched off. When power is restored, the controller will automatically restart.

⚠️ **WARNING!**

High voltage in the controller can cause severe injury or death. Before servicing, turn power off and remove the power cable.

<table>
<thead>
<tr>
<th>Technical Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Mains Supply:</strong></td>
</tr>
<tr>
<td>Voltage</td>
</tr>
<tr>
<td>Frequency</td>
</tr>
<tr>
<td>Power</td>
</tr>
<tr>
<td><strong>Outputs:</strong></td>
</tr>
<tr>
<td>Voltage</td>
</tr>
<tr>
<td>Current</td>
</tr>
<tr>
<td>Power</td>
</tr>
<tr>
<td><strong>Operating Temperature</strong></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td><strong>Storage Temperature</strong></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td><strong>Mains fuses</strong></td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
Connectors Description

The C.U. has connectors for the following functions:

- **Mains connection:** Plug IEC type with integrated fuses for 200V 50Hz supply
- **Connections to the Pump:** J1, Fisher D105A049 type connector

**Connector I/O:** J2, Delta type 25 pin female:

<table>
<thead>
<tr>
<th>N.Pin</th>
<th>Description</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>14</td>
<td>Output +24Vcc</td>
<td>Supply voltage</td>
</tr>
<tr>
<td>1</td>
<td>Input HV ON/OFF positive</td>
<td>Optically Insulated Input</td>
</tr>
<tr>
<td>2</td>
<td>Input HV ON/OFF negative</td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>GND</td>
<td>Supply voltage</td>
</tr>
<tr>
<td>5</td>
<td>FAULT n.o. output</td>
<td></td>
</tr>
<tr>
<td>18</td>
<td>FAULT n.o. output</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>HV ON n.o. output</td>
<td></td>
</tr>
<tr>
<td>19</td>
<td>HV ON n.o. output</td>
<td>RELAY output</td>
</tr>
<tr>
<td>7</td>
<td>PROTECT/START n.o. output</td>
<td></td>
</tr>
<tr>
<td>20</td>
<td>PROTECT/START n.o. output</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>LOCAL/REMOTE n.o. output</td>
<td></td>
</tr>
<tr>
<td>21</td>
<td>LOCAL/REMOTE n.o. output</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>CURRENT analog output positive</td>
<td>Logarithmic analog output</td>
</tr>
<tr>
<td>16</td>
<td>CURRENT analog output GND</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>PRESSURE analog output positive</td>
<td></td>
</tr>
<tr>
<td>17</td>
<td>PRESSURE analog output GND</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>RESERVED</td>
<td>Analog Output</td>
</tr>
</tbody>
</table>

**Serial Connector:** J3, Delta type 9 pin female for RS422

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>6</td>
<td>TX-A (+)</td>
<td>RS 422 output</td>
</tr>
<tr>
<td>8</td>
<td>TX-B (-)</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>RX-A (+)</td>
<td>RS 422 input</td>
</tr>
<tr>
<td>7</td>
<td>RX-B (-)</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>GND</td>
<td>Supply</td>
</tr>
<tr>
<td>9</td>
<td>RESERVED</td>
<td>Input</td>
</tr>
</tbody>
</table>

The Front Panel has a 16 x 2 alphanumeric display and a 4 keys keyboard:

<table>
<thead>
<tr>
<th>Tasto</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>H.V. ON/OFF</td>
<td>Pump supply ON/OFF</td>
</tr>
<tr>
<td>MODE</td>
<td>Working mode configuration</td>
</tr>
<tr>
<td>MEASURE</td>
<td>Selection of the displayed measurement</td>
</tr>
<tr>
<td>CHANGE</td>
<td>Current parameter value change</td>
</tr>
</tbody>
</table>
Display messages related to the pump working condition

When the C.U. is switched on, the display shows:

![Image](autotest.png)

**Main page:** if in Local mode

![Image](local.png)

**If in Remote mode**

![Image](remote.png)

*From this page it is possible to Start the pump or to go to the C.U. configuration.*

**Configuration:** In this condition it is possible to change the operating mode. The configuration is just possible with the HV off. To enter in the Configuration, press the Mode push button

![Image](configuration.png)

Where XXX can be LOC, REM or SERIAL. The corresponding output on the rear panel connector will be: open contact for LOC or SERIAL and closed contact for REM.

The CHANGE push button allows to change the present selection. To confirm the selection and proceed to the following page, press the MODE push button.
Where XXXXX can be PROT or START. The selection is done by means of the CHANGE button.
The corresponding output on the I/O rear panel connector will be: open contact for PROT and closed contact for
START.
Press the MODE push button again to go to the Serial communication Baude Rate selection.

XXX can be 9600, 4800, 1200 or 600 selectable by means of the CHANGE button.
Press the MODE button again to go to the SERIAL address selection page.

XX is the address from 1 to 32 that can be modified by means of the CHANGE button.
To pass from the tens to the units press the MODE button.
Press the MODE button again to go back to the main menu.

Pump in Start: In the following pages the operating mode and the analog values are displayed.
The pump is switched on by pressing the HV ON/OFF push button in Local mode or through the HV ON/OFF input
in REMOTE mode.

If the HV cable is disconnected from the pump, the Error (Fault) condition “Cable Interlock” will be generated.
When the HV cable is connected, the display shows:

Where the Protect indication is shown only if the Protect mode has been selected.
The HV ON output on the Remote I/O connector will be: open contact with HV OFF and closed contact with HV ON.
The MEASURE push button allows to change the page on the display.

Error Condition:
If an Error condition is detected, the FAULT contact on the I/O connector will close.

This message is displayed when the HV Cable is disconnected
This message appears if the measured pump current is continuously higher than 100 mA for a time of 500 msec or longer with the Protect mode selected.

This message appears if the temperature inside the controller is higher than set threshold.

**Pressure indication**
The Pressure indication is calculated from the Current value according to the following relationship.
Analog Outputs
The following graphs give the relationship between the Current and the Pressure versus the Recorder Outputs values.
Serial Communication Description

**Communication Format**
- **8 Data bits**
- No Parity
- 1 Stop bit
- Baud Rate: 600/1200/2400/4800/9600 baud, programmable

**Communication Protocol**
- Master/Slave type (Computer = Host, Controller = Slave)
- Max. number of peripheral units = 32

The communication takes place according to the following scheme:

```
Host    Controller
```
```
Message    Answer
```

**Message Format**

```
<ADR> + <LDAT> + <COM> + <CHAN> + <DATA> + <CRC>
```

Where:
- **<ADR>:** 0x80 + Peripheral unit address (from 0x1 to 0x20)
- **<LDAT>:** COM, CHAN and DATA fields length (coded in decimal on 2 characters) (00 to 99)
- **<COM>:** Capital or non capital letter identifying the command (see the "Command Table") followed by the SubCommand (always 0x30 equivalent to the 0n character)
- **<CHAN>:** Channel number (it is always 0x30, equivalent to 0, for this type of controller)
- **<DATA>:** String of length and content that depend from the command.
  - If the command is a request of reading of a data, this field will contain the "?" (0x3f hexadecimal) character.
  - If the command is a data setting command, or if the message is the answer from the controller to a reading command, this field will contain a data string like shown in the following table.

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Valid Character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Logical</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>1</td>
</tr>
<tr>
<td>Numerical</td>
<td>5 character string completed with &quot;0&quot; characters</td>
</tr>
<tr>
<td>Exponential</td>
<td>String with the following format x.xxSxx</td>
</tr>
</tbody>
</table>

- **<CRC>:** XOR of all the characters of the message, excluding the CRC itself and with the MSB set to 0

The answer structure from the addressed Slave unit, will depend on the received command message:
- No characters if the message has a wrong CRC or a wrong Slave address.
- ACK (0x6 hexadecimal) to confirm the setting of the parameter associated to the command sent by Master, if the command is a writing command
- A message with the same structure as the message described above, but with the <DATA> field that contains the Parameter requested by the Master and with the <ADR> with the MSB set to 0 when the command is a reading command.
- If the message is wrong, the answer will contain the error code identified by the "!" character followed by the "Error Code" coded in decimal on a single character:
- 2: Not existing command
- 4: Not a reading command
- 5: Data not valid
- 6: Out of range value

Command Table
Following is the command table with the description of the allowed operations and the associated data type:

<table>
<thead>
<tr>
<th>Command</th>
<th>Channel</th>
<th>Description</th>
<th>Type</th>
<th>Read/Write</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>L0</td>
<td>0</td>
<td>LOC/REM Configuration</td>
<td>Numerical</td>
<td>R/W</td>
<td>0: Loc, 1: Rem, 2: Serial</td>
</tr>
<tr>
<td>R0</td>
<td>0</td>
<td>PROTECT/START Configuration</td>
<td>Logical</td>
<td>R/W</td>
<td>0: Protect, 1: Start</td>
</tr>
<tr>
<td>A0</td>
<td>0</td>
<td>Address</td>
<td>Numerical</td>
<td>R/W</td>
<td>01 – 32</td>
</tr>
<tr>
<td>O0</td>
<td>0</td>
<td>HV On/Off</td>
<td>Logical</td>
<td>R/W</td>
<td>0: Off, 1: On</td>
</tr>
<tr>
<td>B0</td>
<td>0</td>
<td>Baud Rate</td>
<td>Numerical</td>
<td>R/W</td>
<td>0: 600baud, 1: 1200baud, 2: 2400baud, 3: 4800baud, 4: 9600baud</td>
</tr>
<tr>
<td>I0</td>
<td>0</td>
<td>Current Measurement</td>
<td>Exponential</td>
<td>R</td>
<td>x.xE-x</td>
</tr>
<tr>
<td>F0</td>
<td>0</td>
<td>Pressure Measurement</td>
<td>Exponential</td>
<td>R</td>
<td>x.xE-x</td>
</tr>
<tr>
<td>S0</td>
<td>0</td>
<td>Status</td>
<td>Numerical</td>
<td>R</td>
<td>0: Stop, 1: Start, 2: Fault</td>
</tr>
<tr>
<td>E0</td>
<td>0</td>
<td>Error Code</td>
<td>Numerical</td>
<td>R</td>
<td>0: No err, 1: Overcurrent, 2: Overtemp, 3: interlock</td>
</tr>
<tr>
<td>f0</td>
<td>0</td>
<td>Crv memory</td>
<td>Numerical</td>
<td>R</td>
<td>Flash memory Crc16</td>
</tr>
</tbody>
</table>

Data type:
- Logical: 1 character data field (0/1)
- Exponential: Numerical data field (x.xExxx)
- Numerical: Numerical data field (xxxxxx)

Serial communication examples
HV ON command by Serial line with controller in Serial mode
0x81 0x30 0x34 0x4F 0x30 0x30 0x31 0x7B

Answer from the control unit:
0x06

Pressure reading request:
0x81 0x30 0x34 0x50 0x30 0x30 0x33F 0x6A

Answer from the control unit:
0x01 0x31 0x30 0x50 0x30 0x30 0x34 0x2E 0x31 0x45 0x2D 0x30 0x35 0x16
Interconnections schematic

FEMALE CONNECTOR

I/O

J2

13
12
11
10
9
8
7
6
5
4
3
2
1

OUT LOCAL/REMOTE (RELAY CONTACT N.O.)
OUT LOCAL/REMOTE (RELAY CONTACT N.O.)
OUT PROTECT/START (RELAY CONTACT N.O.)
OUT PROTECT/START (RELAY CONTACT N.O.)
OUT HV ON (RELAY CONTACT N.O.)
OUT FAULT (RELAY CONTACT N.O.)
CURRENT (GND ANALOG OUT)
CURRENT (+ ANALOG OUT)
GROUND
HV ON/OFF (INPUT)
+ 24 VDC 30 mA
+ HV ON/OFF (INPUT)

CURRENT LOGARITHMIC OUTPUT: 0V=100mA \(\text{V}=100\text{mA}
PRESSURE LOGARITHMIC OUTPUT:
RELAY CONTACT: 24V 100mA

ANALOG OUTPUT CONFIGURATION

OUTPUT CONFIGURATION

INPUT CONFIGURATION

FEMALE CONNECTOR

J3

RS 422

1
2
3
4
5

GND
TX-A = (INPUT RS 422)
TX-B = (OUTPUT RS 422)
TX-B = (INPUT RS 422)
TX-A = (OUTPUT RS 422)